

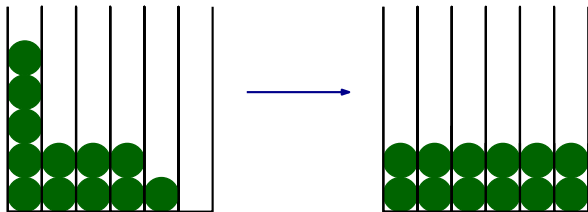
Load Balancing via Randomized Local Search

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and Abbas Mehrabian

University of British Columbia and Simon Fraser University

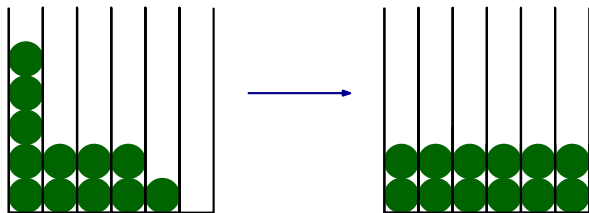
University of Waterloo, 20 May 2016

Load balancing



Want to re-allocate the balls into bins in order to achieve **perfect** balance quickly.

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- ✓ **Desirable**: distributed protocol
- ✓ Bin-controlled vs. ball-controlled (selfish) protocols
- ✓ Synchronous vs. asynchronous protocols
- ✓ **Desirable**: no global knowledge
- ✓ **Desirable**: simplicity
- ✓ **Randomization** often helps!

Informal protocol description

Randomized local search: Each ball acts independently; at **random times**, it chooses a random bin and moves there if its own **load** is improved by doing so.

[Paul Goldberg'04]

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Simple, distributed, asynchronous, randomized, ball-controlled

Comparison with other ball-controlled protocols

n = number of bins, m = number of balls

- ✓ Synchronous protocol, balls know m/n : $O(\ln \ln m + \ln n)$
Even-Dar and Mansour'05
- ✓ Synchronous protocol, no global knowledge: $O(\ln \ln m + n^4)$
Berenbrink, Friedetzky, Goldberg, Goldberg, Hu, Martin'07
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- ✓ Randomized local search (asynchronous, no global knowledge)
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 $O(\ln(n)^2 + \ln(n) \cdot n^2/m)$
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We show the balancing time is indeed $O(\ln n + n^2/m)$

Formal protocol description

Randomized local search:

- 1 Each ball has an **exponential clock** of rate 1. When the clock rings, the ball is **activated**.
- 2 On activation, the ball chooses a random bin and moves there if its own load is improved by doing so.

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Let X_1, \dots, X_m be independent exponentials with rate 1, and let Z be their minimum.

- ✓ Z is exponential with rate m , so $\mathbb{E}Z = 1/m$.
- ✓ $\Pr(Z = X_1) = \Pr(Z = X_2) = \dots = 1/m$

If you start looking at the process at any time, the waiting time for the next ball to be activated is exponential and has mean $1/m$, and the next activated ball is a uniformly random ball.

Formal protocol description

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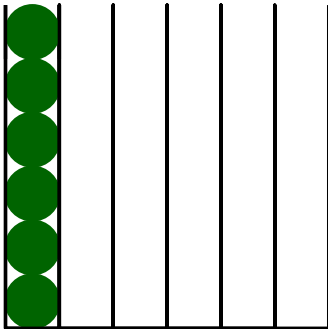
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Theorem (Berenbrink, Kling, Liaw and M'16+)

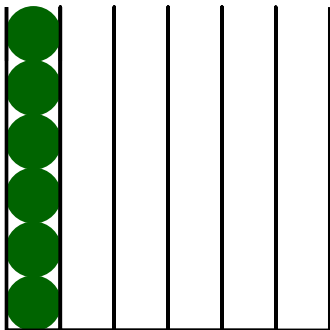
Consider a system of n bins and m balls in an arbitrary initial configuration. Let T be the time to reach a perfectly balanced configuration. We have $\mathbb{E}T \leq O(\ln n + n^2/m)$ and with probability at least $1 - 1/n$, we have $T \leq O(\ln n + \ln n \cdot n^2/m)$.

Tight modulo constants in the big Oh

Tightness of our bound: $\mathbb{E}T \leq O(\ln n + n^2/m)$



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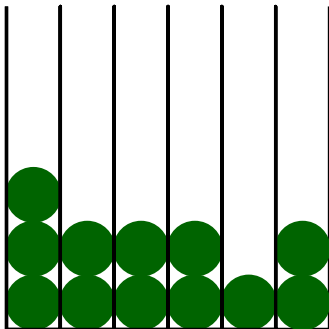


At least $m - m/n$ balls from bin 1 need to be activated:

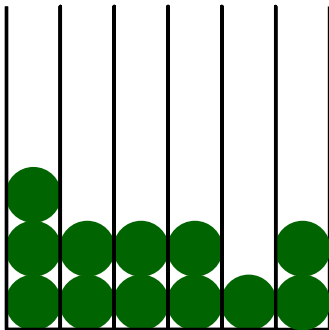
$$\frac{1}{m} + \frac{1}{m-1} + \cdots + \frac{1}{\frac{m}{n} + 1} = H_m - H_{m/n} \approx \ln m - \ln(m/n) = \ln n$$

This shows $\mathbb{E}T \geq \ln n$.

Tightness of our bound: $\mathbb{E}T \leq O(\ln n + n^2/m)$

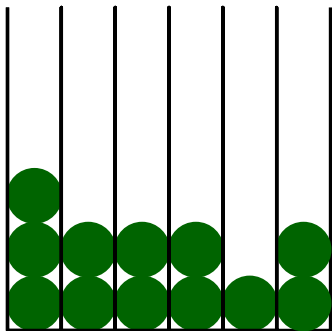


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Some ball in bin 1 needs to be activated and choose bin 5.

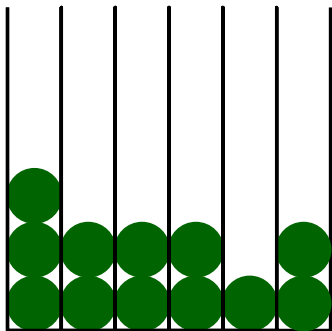
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expected waiting time for some ball in bin 1 to be activated = $\frac{1}{\frac{m}{n}+1}$
expected number of attempts to choose the correct bin = n

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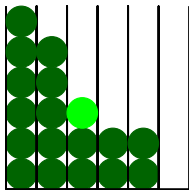
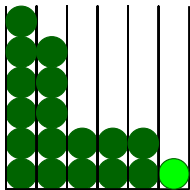
shows $\mathbb{E}T \geq \frac{n}{\frac{m}{n}+1} \geq n^2/2m$

Proof of main result

expected **balancing time** of any initial configuration

$$\leq O(\ln n + n^2/m)$$

A key lemma



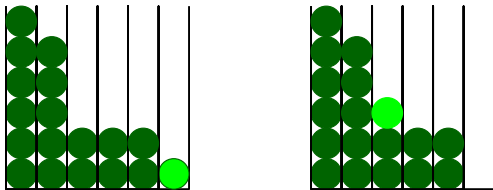
Balancing time of left configuration $\stackrel{st}{\leq}$ Balancing time of right configuration

$\varnothing := m/n$

Discrepancy of a configuration = maximum difference between load of a bin and the average load = $\max\{\ell_{\max} - \varnothing, \varnothing - \ell_{\min}\}$.

Perfect balance \equiv discrepancy zero

A key lemma



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Lemma (The key lemma)

For any $t \geq 0$, consider the configuration $\ell(t)$ resulting from our protocol at time t . Let $\tilde{\ell}(t)$ denote the configuration resulting from our protocol at time t under the presence of an adversary who performs an arbitrary number of destructive moves at arbitrary times. Then

$$\text{disc}(\ell(t)) \stackrel{st}{\leq} \text{disc}(\tilde{\ell}(t)).$$

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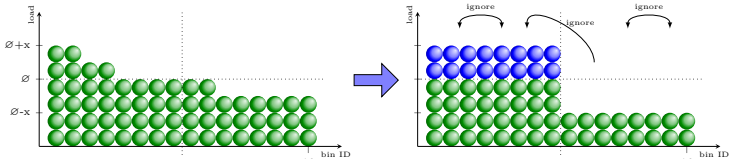
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Helps in two ways: (1) we may do some destructive moves to make “well-shaped” configurations that are simpler to analyse.



A key lemma

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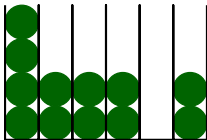
Discrepancy of a configuration = maximum difference between load of a bin and the average load = $\max\{\ell_{\max} - \frac{m}{n}, \frac{m}{n} - \ell_{\min}\}$.

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Helps in two ways: (2) we may “ignore” certain (at the moment unwanted) moves made by the protocol



Analysis outline

- ✓ Initial discrepancy is $m - \epsilon$, want to reduce to 0
- ✓ In the zeroth phase, discrepancy is reduced to ϵ
What happens: $m - \epsilon$ balls leave bin 1
Running time of zeroth phase $\leq O(\ln n)$
- ✓ In the first phase, discrepancy is reduced to $O(\ln n)$
What happens: in each subphase, all loads get much closer to ϵ simultaneously
Running time of first phase $\leq O(\ln n)$
- ✓ In the second phase, discrepancy is reduced to 0
What happens: in each step, we get just one ball closer to perfect balance
Running time of second phase $\leq O(n^2/m)$
- ✓ Total running time $\leq O(\ln n + n^2/m)$

First phase

Lemma

For any $x \geq 4 \ln n$, the expected time to reduce discrepancy from x to $\sqrt{4x \ln n}$ is $\leq \ln\left(\frac{\varnothing+x}{\varnothing-x}\right)$

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We have

$$\ln(\varnothing + x) - \ln(\varnothing - x) = \ln\left(1 + \frac{2x}{\varnothing - x}\right) \leq \frac{2x}{\varnothing - x} \leq 4x/\varnothing$$

Straightforward calculations give

$$\begin{aligned} \frac{4x}{\varnothing} + \frac{4\sqrt{4x \ln n}}{\varnothing} + \dots &\leq \frac{16 \ln n}{\varnothing} \left(x + \sqrt{x} + \sqrt{\sqrt{x}} + \dots \right) \\ &\leq O(x \cdot \ln n / \varnothing) = O(\ln n) \end{aligned}$$

is the expected time to bring discrepancy down to $O(\ln n)$, hence completing the first phase.

First phase

(Chernoff bound)

Let X be a sum of independent 0, 1-random variables. For any $\varepsilon \in [0, 1]$ we have

$$\Pr(|X - \mathbb{E}X| > \varepsilon \mathbb{E}X) < 2e^{-\varepsilon^2 \mathbb{E}X/3}$$

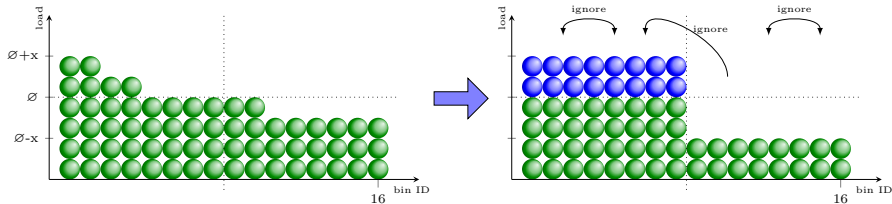
In particular, if $\mathbb{E}X \geq 4 \ln n$,

$$\Pr(|X - \mathbb{E}X| > \sqrt{4 \ln n \cdot \mathbb{E}X}) < n^{-2}$$

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Activation probability of a ball = $1 - \exp(-t) =: p$.

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Activation probability of a ball = $1 - \exp(-t) =: p$.

Consider a heavy bin.

Each of its balls is activated with probability p , and moves to a light bin with probability $1/2$.

So the number of balls it loses is a sum of independent $\{0, 1\}$ -random variables and has mean = $(\varnothing + x) \times p/2 = x$.

By Chernoff, with probability $\geq 1 - n^{-2}$ this bin loses between

$[x - \sqrt{4x \ln n}, x + \sqrt{4x \ln n}]$ balls, and so will have between $\varnothing - \sqrt{4x \cdot \ln n}$ and $\varnothing + \sqrt{4x \cdot \ln n}$ balls at time t .

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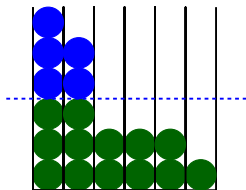
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A similar reasoning works for a light bin.

Second phase



Lemma

Assuming discrepancy is $O(\ln n)$, the average time to reduce the number of *overloaded balls* to n is $\leq O(n(\ln n)^2/m)$.

Lemma

Assuming the number of overloaded balls is n , the average time to reduce the discrepancy to 1 is $\leq O(n^2/m)$.

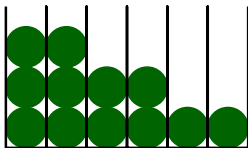
Lemma

Assuming the discrepancy is 1, the average time to reduce discrepancy to 0 is $\leq O(n^2/m)$.

Second phase

Lemma

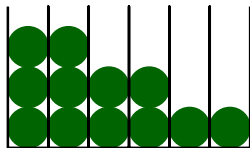
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There are A bins of load $> \varnothing$, and so there are also A bins of load $< \varnothing$.

If $A \geq 1$ there are $(\varnothing + 1) \cdot A$ balls that, when activated, find an underloaded bin with probability A/n .

The expected time for such a move to happen is $\frac{1}{A \cdot (\varnothing + 1)} \cdot \frac{1}{A/n} \leq \frac{n}{\varnothing \cdot A^2}$

The expected total time to balance out is less than

$$\sum_{A=1}^{\infty} \frac{n}{\varnothing \cdot A^2} = \frac{\pi^2}{6} \times \frac{n}{\varnothing} = O(n^2/m)$$

So we have

expected **balancing time** of any initial configuration

$$\leq O(\ln n + n^2/m)$$

We now briefly consider the case where bins have different speeds...

Non-uniform-speed setting

Load of a bin = number of balls divided by bin's speed

Non-uniform-speed setting

Load of a bin = number of balls divided by bin's **speed**

Let \mathbf{s} denote the speeds vector, let $\mathbf{p} \in [0, 1]^n$ be a probability distribution, and let $\mathbf{q} \in [0, 1]^n$ be arbitrary.

GRLS($m, n, \mathbf{s}, \mathbf{p}, \mathbf{q}$)

(code executed by an activated ball in bin i)

sample random bin i' according to \mathbf{p}

with probability $q_{i'}$, do the following:

$l_{\text{cur}} \leftarrow$ current load of bin i

$l_{\text{new}} \leftarrow$ load of bin i' in case the ball moved to bin i'

if $l_{\text{new}} \leq l_{\text{cur}}$: move to bin i'

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$$\begin{aligned} \mathcal{T}(\text{RLS}(m, n, \mathbf{s})) &\stackrel{st}{\leq} \mathcal{T}\left(\text{GRLS}\left(m, n, \mathbf{s}, \frac{\mathbf{1}}{n}, \frac{\mathbf{s}}{s_{\max}}\right)\right) \\ &\stackrel{d}{=} \frac{ns_{\max}}{S} \cdot \mathcal{T}\left(\text{GRLS}\left(m, n, \mathbf{s}, \frac{\mathbf{s}}{S}, \mathbf{1}\right)\right) \\ &\stackrel{st}{\leq} \frac{ns_{\max}}{S} \mathcal{T}(\text{RLS}(m, n, \mathbf{1})) \end{aligned}$$

Non-uniform-speeds setting

Theorem (Berenbrink, Kling, Liaw and M'16+)

Consider a system of n bins (with speeds) and m identical balls in an arbitrary initial configuration. Assume that the minimum speed is 1, and let s_{\max} and S denote the maximum speed and the sum of speeds, respectively. Let T be the time to reach a perfectly balanced configuration. We have

$$\mathbb{E}T = O(\ln(S) \cdot ns_{\max}/S + s_{\max}S \cdot n/m)$$

and with probability $\geq 1 - 1/n$ we have

$$T = O(\ln(S) \cdot ns_{\max}/S + \ln(n) \cdot s_{\max}S \cdot n/m).$$

If bins are identical, $s_{\max} = 1$ and $S = n$, so $\mathbb{E}T = O(\ln n + n^2/m)$.